

METHODOLOGY

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Quantitative evidence synthesis: a practical guide on meta-analysis, meta-regression, and publication bias tests for environmental sciences

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Abstract ³

Meta-analysis is a quantitative way of synthesizing results from multiple studies to obtain reliable evidence of an intervention or phenomenon. Indeed, an increasing number of meta-analyses are conducted in environmental sciences, and resulting meta-analytic evidence is often used in environmental policies and decision-making. We conducted a survey of recent meta-analyses in environmental sciences and found poor standards of current meta-analytic practice and reporting. For example, only ~40% of the 73 reviewed meta-analyses reported heterogeneity (variation among effect sizes beyond sampling error), and publication bias was assessed in fewer than half. Furthermore, although almost all the meta-analyses had multiple effect sizes originating from the same studies, non-independence among effect sizes was considered in only half of the meta-analyses. To improve the implementation of meta-analysis in environmental sciences, we here outline practical guidance for conducting a meta-analysis in environmental sciences. We describe the key concepts of effect size and meta-analysis and detail procedures for fitting multilevel meta-analysis and meta-regression models and performing associated publication bias tests. We demonstrate a clear need for environmental scientists to embrace multilevel meta-analytic models, which explicitly model dependence among effect sizes, rather than the commonly used random-effects models. Further, we discuss how reporting and visual presentations of meta-analytic results can be much improved by following reporting guidelines such as PRISMA-EcoEvo (Preferred Reporting Items for Systematic Reviews and Meta-Analyses for Ecology and Evolutionary Biology). This paper, along with the accompanying online tutorial, serves as a practical guide on conducting a complete set of meta-analytic procedures (i.e., meta-analysis, heterogeneity quantification, meta-regression, publication bias tests and sensitivity analysis) and also as a gateway to more advanced, yet appropriate, methods.

Keywords Hierarchical models, Robust variance estimation, Spatial dependency, Variance–covariance matrix, Meta-analysis of variance, Missing data, Network meta-analysis, Multivariate meta-analysis ⁵

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Background 1

Evidence synthesis is an essential part of science. The method of systematic review provides the most trusted and unbiased way to achieve the synthesis of evidence [1–3]. Systematic reviews often include a quantitative summary of studies on the topic of interest, referred to as a meta-analysis (for discussion on the definitions of ‘meta-analysis’, see [4]). The term meta-analysis can also mean a set of statistical techniques for quantitative data synthesis. The methodologies of the meta-analysis were initially developed and applied in medical and social sciences. However, meta-analytic methods are now used in many other fields, including environmental sciences [5–7]. In environmental sciences, the outcomes of meta-analyses (within systematic reviews) have been used to inform environmental and related policies (see [8]). Therefore, the reliability of meta-analytic results in environmental sciences is important beyond mere academic interests; indeed, incorrect results could lead to ineffective or sometimes harmful environmental policies [8].

As in medical and social sciences, environmental scientists frequently use traditional meta-analytic models, namely fixed-effect and random-effects models [9, 10]. However, we contend that such models in their original formulation are no longer useful and are often incorrectly used, leading to unreliable estimates and errors. This is mainly because the traditional models assume independence among effect sizes, but almost all primary research papers include more than one effect size, and this non-independence is often not considered (e.g., [11–13]). Furthermore, previous reviews of published meta-analyses in environmental sciences (hereafter, ‘environmental meta-analyses’) have demonstrated that less than half report or investigate heterogeneity (inconsistency) among effect sizes [14–16]. Many environmental meta-analyses also do not present any sensitivity analysis, for example, for publication bias (i.e., statistically significant effects being more likely to be published, making collated data unreliable; [17, 18]). These issues might have arisen for several reasons, for example, because of no clear conduct guideline for the statistical part of meta-analyses in environmental sciences and rapid developments in meta-analytic methods. Taken together, the field urgently requires a practical guide to implement correct meta-analyses and associated procedures (e.g., heterogeneity analysis, meta-regression, and publication bias tests; cf. [19]).

To assist environmental scientists in conducting meta-analyses, the aims of this paper are five-fold. First, we provide an overview of the processes involved in a meta-analysis while introducing some key concepts. Second, after introducing the main types of effect size measures, we mathematically describe the two commonly used traditional meta-analytic models, demonstrate their utility,

and introduce a practical, multilevel meta-analytic model for environmental sciences that appropriately handles non-independence among effect sizes. Third, we show how to quantify heterogeneity (i.e., consistencies among effect sizes and/or studies) using this model, and then explain such heterogeneity using meta-regression. Fourth, we show how to test for publication bias in a meta-analysis and describe other common types of sensitivity analysis. Fifth, we cover other technical issues relevant to environmental sciences (e.g., scale and phylogenetic dependence) as well as some advanced meta-analytic techniques. In addition, these five aims (sections) are interspersed with two more sections, named ‘Notes’ on: (1) visualisation and interpretation; and (2) reporting and archiving. Some of these sections are accompanied by results from a survey of 73 environmental meta-analyses published between 2019 and 2021; survey results depict current practices and highlight associated problems (for the method of the survey, see Additional file 1). Importantly, we provide easy-to-follow implementations of much of what is described below, using the *R* package, *metafor* [20] and other *R* packages at the webpage (https://itchyshin.github.io/Meta-analysis_tutorial/), which also connects the reader to the wealth of online information on meta-analysis (note that we also provide this tutorial as Additional file 2; see also [21]).

Overview with key concepts 6

Statistically speaking, we have three general objectives when conducting a *meta-analysis* [12]: (1) estimating an overall mean, (2) quantifying consistency (*heterogeneity*) between studies, and (3) explaining the heterogeneity (see Table 1 for the definitions of the terms in *italic*). A notable feature of a meta-analysis is that an overall mean is estimated by taking the *sampling variance* of each *effect size* into account: a study (effect size) with a low sampling variance (usually based on a larger sample size) is assigned more weight in estimating an overall mean than one with a high sampling variance (usually based on a smaller sample size). However, an overall mean estimate itself is often not informative because one can get the same overall mean estimates in different ways. For example, we may get an overall estimate of zero if all studies have zero effects with no heterogeneity. In contrast, we might also obtain a zero mean across studies that have highly variable effects (e.g., ranging from strongly positive to strongly negative), signifying high heterogeneity. Therefore, quantifying indicators of heterogeneity is an essential part of a meta-analysis, necessary for interpreting the overall mean appropriately. Once we observe non-zero heterogeneity among effect sizes, then, our job is to explain this variation by running *meta-regression* models, and, at the same time, quantify how much variation

Table 1 Definitions of key concepts and associated statistical parameters, which are used in formulas in the main text **1**

Term	Definition (with associated parameters, if any)
Effect size	A measurement of effect (usually state of a single group, comparison between groups, or association, see Table 2). In a meta-analytic model, it becomes the response variable (noted as z_i in the formulas)
Sampling variance	A measure of uncertainty in effect size (noted as v_i). Its inverse is often called ‘weight’ (the square-root of weight is ‘precision’, and the square root of sampling variance is ‘sampling standard error’)
Meta-analysis	A statistical method to aggregate effect sizes from studies on the same or similar topics, by assigning different weights based on sampling variance of effect sizes. Strictly speaking, in a formal (weighted) meta-analysis, sampling variance needs to be incorporated and it is assumed to be known (Table 2)
Overall mean (effect)	An average effect size based on a meta-analytic model (noted as β_0 and its standard errors, $se(\beta_0)$)
Heterogeneity	An indicator of consistency among effect sizes, or an extent of variation around the overall effect (β_0); heterogeneity can be quantified by absolute measures, such as τ^2 , or relative measures, such as I^2
Meta-regression	A regression model which extends a meta-analytic model with a moderator(s), aiming to explain heterogeneity (quantified as R^2) and quantifying the effect of a moderator (noted as, for example, β_1)
Publication bias tests	A set of statistical methodologies to detect and correct for publication bias, where a subset of results (positive findings) is more likely to be published and present in the meta-analytic dataset than otherwise
Sensitivity analysis	A set of statistical analyses that checks the robustness of one’s main analysis; if sensitivity analysis shows different results (qualitatively and/or quantitatively), then we must doubt the robustness of the main findings

is accounted for (often quantified as R^2). In addition, it is important to conduct an extra set of analyses, often referred to as *publication bias tests*, which are a type of *sensitivity analysis* [11], to check the robustness of meta-analytic results.

Choosing an effect size measure **4**

In this section, we introduce different kinds of ‘effect size measures’ or ‘effect measures’. In the literature, the term ‘effect size’ is typically used to refer to the magnitude or strength of an effect of interest or its biological interpretation (e.g., environmental significance). Effect sizes can be quantified using a range of measures (for details, see [22]). In our survey of environmental meta-analyses (Additional file 1), the two most commonly used effect size measures are: the logarithm of response ratio, $\ln RR$ ([23]; also known as the ratio of means; [24]) and standardized mean difference, SMD (often referred to as Hedges’ g or Cohen’s d [25, 26]). These are followed by proportion (%) and Fisher’s z -transformation of correlation, or Zr . These four effect measures nearly fit into the three categories, which are named: (1) single-group measures (a statistical summary from one group; e.g., proportion), (2) comparative measures (comparing between two groups e.g., SMD and $\ln RR$), and (3) association measures (relationships between two variables; e.g., Zr). Table 2 summarizes effect measures that are common or potentially useful for environmental scientists. It is important to note that any measures with sampling variance can become an ‘effect size’. The main reason why SMD , $\ln RR$, Zr , or proportion are popular effect measures is that they are unitless, while a meta-analysis of mean, or mean difference, can only be conducted when all effect sizes have the same unit (e.g., cm, kg).

Table 2 also includes effect measures that are likely to be unfamiliar to environmental scientists; these are effect sizes that characterise differences in the observed variability between samples, (i.e., $\ln SD$, $\ln CV$, $\ln VR$ and $\ln CVR$; [27, 28]) rather than central tendencies (averages). These dispersion-based effect measures can provide us with extra insights along with average-based effect measures. Although the literature survey showed none of these were used in our sample, these effect sizes have been used in many fields, including agriculture (e.g., [29]), ecology (e.g., [30]), evolutionary biology (e.g., [31]), psychology (e.g., [32]), education (e.g., [33]), psychiatry (e.g., [34]), and neurosciences (e.g. [35]),. Perhaps, it is not difficult to think of an environmental intervention that can affect not only the mean but also the variance of measurements taken on a group of individuals or a set of plots. For example, environmental stressors such as pesticides and eutrophication are likely to increase variability in biological systems because stress accentuates individual differences in environmental responses (e.g. [36, 37],). Such ideas are yet to be tested meta-analytically (cf. [38, 39]).

Choosing a meta-analytic model **7**

Fixed-effect and random-effects models **8**

Two traditional meta-analytic models are called the ‘fixed-effect’ model and the ‘random-effects’ model. The former assumes that all effect sizes (from different studies) come from one population (i.e., they have one true overall mean), while the latter does not have such an assumption (i.e., each study has different overall means or heterogeneity exists among studies; see below for more). The fixed-effect model, which should probably be

Table 2 Selected list of effect size measures and their sampling variances, belonging to three types: (1) single-group effect, (2) comparative effect and (3) association effect

Type	Effect size	Point estimate	Sampling variance estimate	Reference
Single group	Mean	\bar{x}_i	s_i^2/n_i	[134]
Single group	Proportion	$p_i = \frac{y_i}{n_i}$	$\frac{p_i(1-p_i)}{n_i} = \frac{y_i(n_i-y_i)}{n_i^3}$	[134]
Single group	Log standard deviation (lnSD)	$\ln s_i$	$\frac{1}{2(n_i-1)}$	[27]
Single group	Log coefficient of variation (lnCV)	$\ln\left(\frac{s_i}{\bar{x}_i}\right)$	$\frac{s_i^2}{n_i \bar{x}_i^2} + \frac{1}{2(n_i-1)}$	[27]
Comparative	Mean difference (MD)	$\bar{x}_{iT} - \bar{x}_{iC}$	$\frac{s_{iT}^2}{n_{iT}} + \frac{s_{iC}^2}{n_{iC}}$	[134]
Comparative	Standardised mean difference (SMD)	$d_i = \frac{\bar{x}_{iT} - \bar{x}_{iC}}{\sqrt{\frac{(n_{iC}-1)s_{iC}^2 + (n_{iT}-1)s_{iT}^2}{n_{iC} + n_{iT} - 2}}}$	$\frac{1}{n_{iC}} + \frac{1}{n_{iT}} + \frac{d_i^2}{2(n_{iC} + n_{iT})}$	[25]
Comparative	Risk (proportion) difference (RD)	$\frac{y_{iT}}{n_{iT}} - \frac{y_{iC}}{n_{iC}}$	$\frac{y_{iT}(n_{iT}-y_{iT})}{n_{iT}^3} + \frac{y_{iC}(n_{iC}-y_{iC})}{n_{iC}^3}$	[134]
Comparative	Log odds ratio (lnOR)	$\ln\left(\frac{y_{iT}/n_{iT}}{n_{iT}-y_{iT}}\right) - \ln\left(\frac{y_{iC}/n_{iC}}{n_{iC}-y_{iC}}\right)$	$\frac{1}{y_{iT}} + \frac{1}{n_{iT}-y_{iT}} + \frac{1}{y_{iC}} + \frac{1}{n_{iC}-y_{iC}}$	[134]
Comparative	Log response ratio (lnRR)	$\ln\left(\frac{\bar{x}_{iT}}{\bar{x}_{iC}}\right)$	$\frac{s_{iC}^2}{n_{iC} \bar{x}_{iC}^2} + \frac{s_{iT}^2}{n_{iT} \bar{x}_{iT}^2}$	[135]
Comparative	Log variability ratio (lnVR)	$\ln\left(\frac{s_{iT}}{s_{iC}}\right)$	$\frac{1}{2(n_{iC}-1)} + \frac{1}{2(n_{iT}-1)}$	[27]
Comparative	Log coefficient of variation ratio (lnCVR)	$\ln\left(\frac{s_{iT}}{\bar{x}_{iT}}\right) - \ln\left(\frac{s_{iC}}{\bar{x}_{iC}}\right)$	$\frac{s_{iC}^2}{n_{iC} \bar{x}_{iC}^2} + \frac{1}{2(n_{iC}-1)} + \frac{s_{iT}^2}{n_{iT} \bar{x}_{iT}^2} + \frac{1}{2(n_{iT}-1)}$	[27]
Association	Fisher's z-transformation of correlation, r (Zr)	$\frac{1}{2} \ln\left(\frac{1+r_i}{1-r_i}\right)$	$\frac{1}{n_i-3}$	[134]

For the column 3rd and 4th, notations represent: \bar{x} (mean), s (standard deviation), n (sampling size), y (the number of events), the subscript T (treatment group), the subscript C (control group) and the subscript i (the i th effect size or study)

Note that better estimators may be found in the relevant references; for example, SMD can be best estimated by multiplying by $\left(1 - \frac{3}{4(n_{iC} + n_{iT} - 2) - 1}\right)$, and see also [43]

more correctly referred to as the ‘common-effect’ model, can be written as [9, 10, 40]:

$$z_j = \beta_0 + m_j, \quad (1)$$

$$m_j \sim N(0, v_j),$$

where the intercept, β_0 is the overall mean, z_j (the response/dependent variable) is the effect size from the j th study ($j=1, 2, \dots, N_{study}$; in this model, N_{study} =the number of studies=the number of effect sizes), m_j is the sampling error, related to the j th sampling variance (v_j), which is normally distributed with the mean of 0 and the ‘study-specific’ sampling variance, v_j (see also Fig. 1A).

The overall mean needs to be estimated and often done so as the weighted average with the weights, $w_j = 1/v_j$ (i.e., the inverse-variance approach). An important, but sometimes untenable, assumption of meta-analysis is that sampling variance is known. Indeed, we estimate sampling variance, using formulas, as in Table 2, meaning that v_j is submitted by sampling variance estimates (see also section ‘Scale dependence’). Of relevance, the use of the inverse-variance approach has been recently criticized, especially for SMD and lnRR [41, 42] and we note that the inverse-variance approach using the formulas in Table 2 is one of several different weighting approaches used in meta-analysis (e.g., for adjusted

sampling-variance weighing, see [43, 44]; for sample-size-based weighting, see [41, 42, 45, 46]). Importantly, the fixed-effect model assumes that the only source of variation in effect sizes (z_j) is the effect due to sampling variance (which is inversely proportional to the sample size, n ; Table 2).

Similarly, the random-effects model can be expressed as:

$$z_j = \beta_0 + u_j + m_j, \quad (2)$$

$$u_j \sim N(0, \tau^2), \text{ \& } m_j \sim N(0, v_j),$$

where u_j is the j th study effect, which is normally distributed with the mean of 0 and the between-study variance, τ^2 (for different estimation methods, see [47–50]), and other notations are the same as in Eq. 1 (Fig. 1B). Here, the overall mean can be estimated as the weighted average with weights $w_j = 1/(\tau^2 + v_j^2)$ (note that different weighting approaches, mentioned above, are applicable to the random-effects model and some of them are to the multilevel model, introduced below). The model assumes each study has its specific mean, $\beta_0 + u_j$, and (in)consistencies among studies (effect sizes) are indicated by τ^2 . When τ^2 is 0 (or not statistically different from 0), the random-effects model simplifies to the fixed-effect model

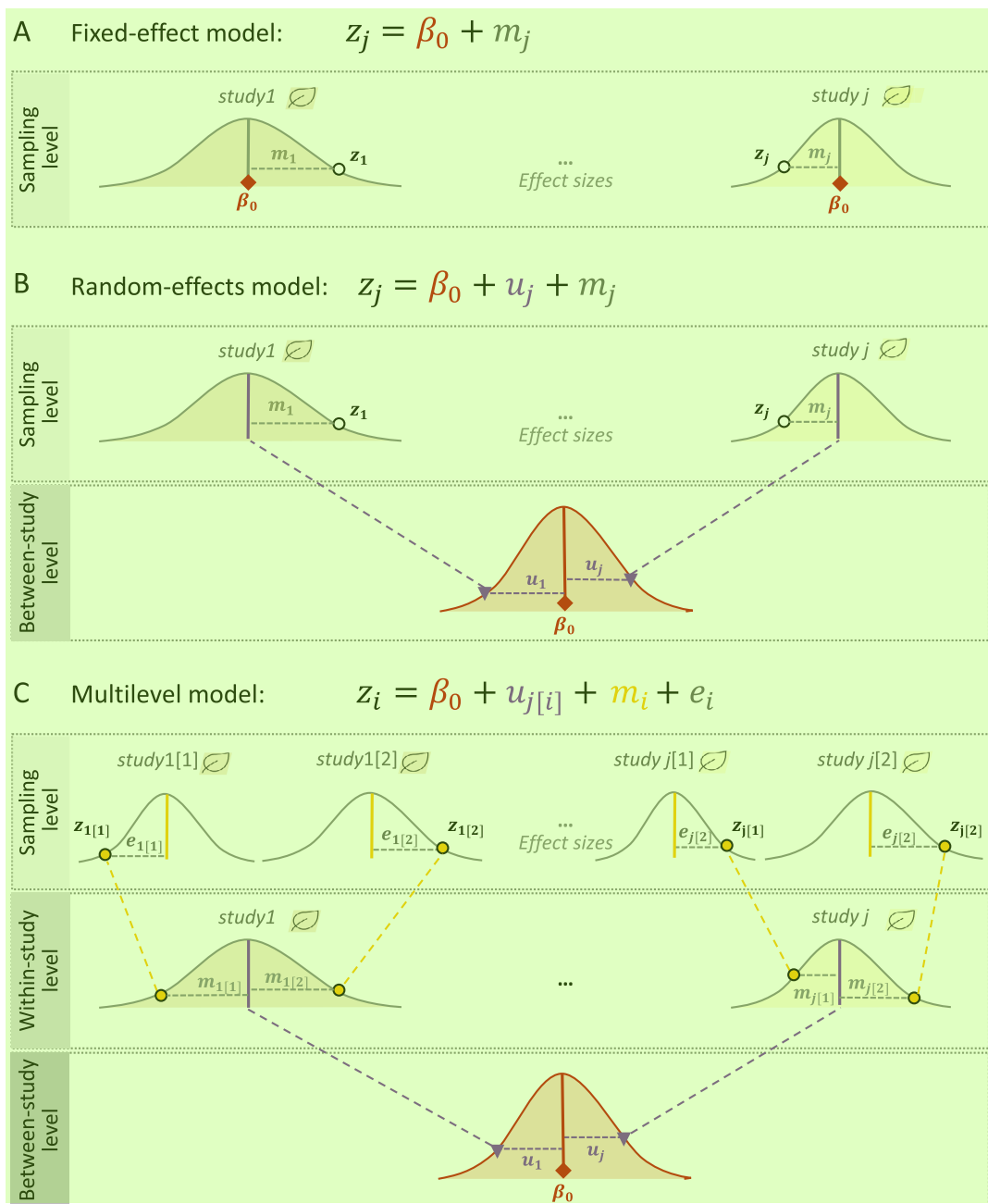


Fig. 1 Visualisation of the three statistical models of meta-analysis: **A** a fixed-effect model (1-level), **B** a random-effects model (2-level), and **C** a multilevel model (3-level; see the text for what symbols mean)

(cf. Equations 1 and 2). Given no studies in environmental sciences are conducted in the same manner or even at exactly the same place and time, we should expect different studies to have different means. Therefore, in almost all cases in the environmental sciences, the random-effects model is a more ‘realistic’ model [9, 10, 40]. Accordingly, most environmental meta-analyses (68.5%;

50 out of 73 studies) in our survey used the random-effects model, while only 2.7% (2 of 73 studies) used the fixed-effect model (Additional file 1).

Multilevel meta-analytic models

Although we have introduced the random-effects model as being more realistic than the fixed-effect

model (Eq. 2), we argue that the random-effects model is rather limited and impractical for the environmental sciences. This is because random-effects models, like fixed-effect models, assume all effect sizes (z_j) to be independent. However, when multiple effect sizes are obtained from a study, these effect sizes are dependent (for more details, see the next section on non-independence). Indeed, our survey showed that in almost all datasets used in environmental meta-analyses, this type of non-independence among effect sizes occurred (97.3%; 71 out of 73 studies, with two studies being unclear, so effectively 100%; Additional file 1). Therefore, we propose the simplest and most practical meta-analytic model for environmental sciences as [13, 40] (see also [51, 52]):

$$z_i = \beta_0 + u_{j[i]} + e_i + m_i, \quad (3)$$

$$u_j \sim N(0, \tau^2), e_i \sim N(0, \sigma^2), \text{ \& } m_i \sim N(0, v_i)$$

where we explicitly recognize that $N_{effect} (i=1, 2, \dots, N_{effect}) > N_{study} (j=1, 2, \dots, N_{study})$ and, therefore, we now have the study effect (between-study effect), $u_{j[i]}$ (for the j th study and i th effect size) and effect-size level (within-study) effect, e_i (for the i th effect size), with the between-study variance, τ^2 , and within-study variance, σ^2 , respectively, and other notations are the same as above. We note that this model (Eq. 3) is an extension of the random-effects model (Eq. 2), and we refer to it as the multilevel/hierarchical model (used in 7 out of 73 studies: 9.6% [Additional file 1]; note that Eq. 3 is also known as a three-level meta-analytic model; Fig. 1C). Also, environmental scientists who are familiar with (generalised) linear mixed-models may recognize u_j (the study effect) as the effect of a random factor which is associated with a variance component, i.e., τ^2 [53]; also, e_i and m_i can be seen as parts of random factors, associated with σ^2 and v_i (the former is comparable to the residuals, while the latter is sampling variance, specific to a given effect size).

It seems that many researchers are aware of the issue of non-independence so that they often use average effect sizes per study or choose one effect size (at least 28.8%, 21 out of 73 environmental meta-analyses; Additional file 1). However, as we discussed elsewhere [13, 40], such averaging or selection of one effect size per study dramatically reduces our ability to investigate environmental drivers of variation among effect sizes [13]. Therefore, we strongly support the use of the multilevel model. Nevertheless, this proposed multilevel model, formulated as Eq. 3 does not usually deal with the issue of non-independence completely, which we elaborate on in the next section.

Non-independence among effect sizes and among sampling errors

When you have multiple effect sizes from a study, there are two broad types and three cases of non-independence (cf. [11, 12]): (1) effect sizes are calculated from different cohorts of individuals (or groups of plots) within a study (Fig. 2A, referred to as ‘shared study identity’), and (2) effects sizes are calculated

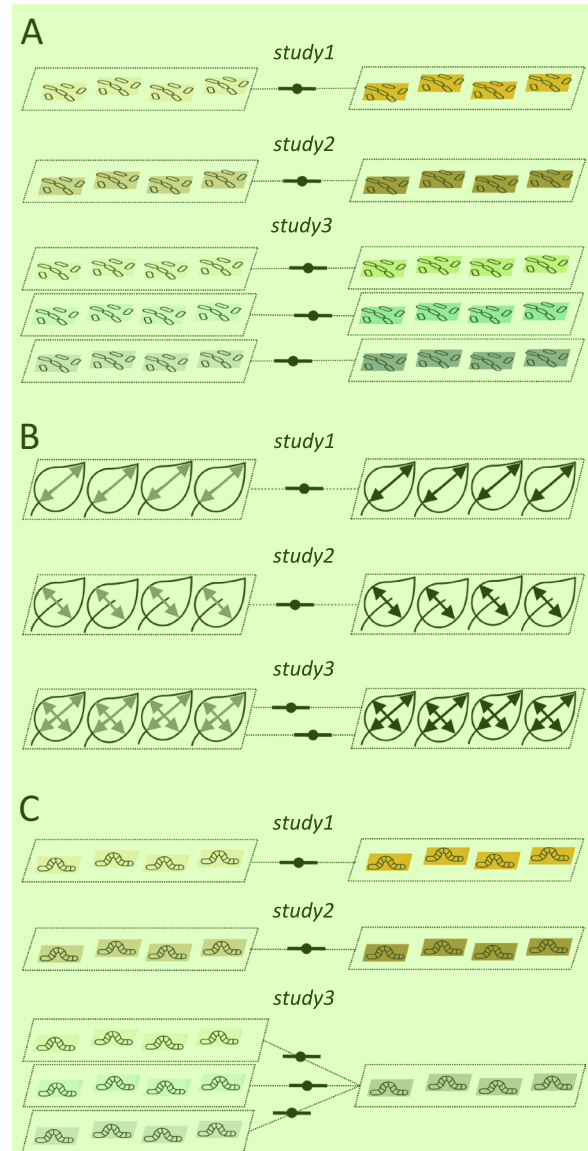


Fig. 2 Visualisation of the three types of non-independence among effect sizes: **A** due to shared study identities (effect sizes from the same study), **B** due to shared measurements (effect sizes come from the same group of individuals/plots but are based on different types of measurements), and **C** due to shared control (effect sizes are calculated using the same control group and multiple treatment groups; see the text for more details)

from the same cohort of individuals (or group of plots; Fig. 2B, referred to as ‘shared measurements’) or *partially* from the same individuals and plots, more concretely, sharing individuals and plots from the control group (Fig. 2C, referred to as ‘shared control group’). The first type of non-independence induces dependence among effect sizes, but not among sampling variances, and the second type leads to non-independence among sampling variances. Many datasets, if not almost all, will have a combination of these three cases (or even are more complex, see the section “Complex non-independence”). Failing to deal with these non-independences will inflate Type 1 error (note that the overall estimate, b_0 is unlikely to be biased, but standard error of b_0 , $se(b_0)$, will be underestimated; note that this is also true for all other regression coefficients, e.g., b_1 ; see Table 1). The multilevel model (as in Eq. 3) only takes care of cases of non-independence that are due to the shared study identity but neither shared measurements nor shared control group.

There are two practical ways to deal with non-independence among sampling variances. The first method is that we explicitly model such dependence using a variance–covariance (VCV) matrix (used in 6 out of 73 studies: 8.2%; Additional file 1). Imagine a simple scenario with a dataset of three effect sizes from two studies where two effects sizes from the first study are

calculated (partially) using the same cohort of individuals (Fig. 2B); in such a case, the sampling variance effect, m_i , as in Eq. 3, should be written as:

$$m_i \sim N(0, \mathbf{M})$$

$$\mathbf{M} = \begin{bmatrix} v_{1[1]} & \rho\sqrt{v_{1[1]}v_{1[2]}} & 0 \\ \rho\sqrt{v_{1[2]}v_{1[1]}} & v_{1[2]} & 0 \\ 0 & 0 & v_{2[3]} \end{bmatrix}, \quad (4)$$

where \mathbf{M} is the VCV matrix showing the sampling variances, $v_{1[1]}$ (study 1 and effect size 1), $v_{1[2]}$ (study 1 and effect size 2), and $v_{2[3]}$ (study 2 and effect size 3) in its diagonal, and sampling covariance, $\rho\sqrt{v_{1[1]}v_{1[2]}} = \rho\sqrt{v_{1[2]}v_{1[1]}}$ in its off-diagonal elements, where ρ is a correlation between two sampling variances due to shared samples (individuals/plots). Once this VCV matrix is incorporated into the multilevel model (Eq. 3), all the types of non-independence, as in Fig. 2, are taken care of. Table 3 shows formulas for the sampling variance and covariance of the four common effect sizes (SDM, lnRR, proportion and Zr). For comparative effect measures (Table 2), exact covariances can be calculated under the case of ‘shared control group’ (see [54, 55]). But this is not feasible for most circumstances because we usually do not know what ρ should be. Some have suggested fixing this value at 0.5 (e.g., [11]) or 0.8 (e.g., [56]); the latter

Table 3 Examples of dependence between two sampling variances (v_1 and v_2) and their covariance for four common effect size statistics

Effect size	Situation	Variances estimate	Covariance estimate
Proportion	Shared measurement	$v_1 = \frac{y_1(n_1 - y_1)}{n_1^2}$ $v_2 = \frac{y_2(n_2 - y_2)}{n_2^2}$	$\rho\sqrt{\frac{y_1(n_1 - y_1)}{n_1^3} \frac{y_2(n_2 - y_2)}{n_2^3}}$
Zr	Shared measurement	$v_1 = \frac{1}{2} \ln\left(\frac{1+r_1}{1-r_1}\right)$ $v_2 = \frac{1}{2} \ln\left(\frac{1+r_2}{1-r_2}\right)$	$\rho\sqrt{\frac{1}{4} \ln\left(\frac{1+r_1}{1-r_1}\right) \ln\left(\frac{1+r_2}{1-r_2}\right)}$
lnRR	Shared measurement	$v_1 = \frac{s_{1C}^2}{n_{1C}\bar{x}_{1C}^2} + \frac{s_{1T}^2}{n_{1T}\bar{x}_{1T}^2}$ $v_2 = \frac{s_{2C}^2}{n_{2C}\bar{x}_{2C}^2} + \frac{s_{2T}^2}{n_{2T}\bar{x}_{2T}^2}$	$\rho\sqrt{\left(\frac{s_{1C}^2}{n_{1C}\bar{x}_{1C}^2} + \frac{s_{1T}^2}{n_{1T}\bar{x}_{1T}^2}\right) \left(\frac{s_{2C}^2}{n_{2C}\bar{x}_{2C}^2} + \frac{s_{2T}^2}{n_{2T}\bar{x}_{2T}^2}\right)}$
	Shared control	$v_1 = \frac{s_{1C}^2}{n_{1C}\bar{x}_{1C}^2} + \frac{s_{1T}^2}{n_{1T}\bar{x}_{1T}^2}$ $v_2 = \frac{s_{1C}^2}{n_{1C}\bar{x}_{1C}^2} + \frac{s_{2T}^2}{n_{2T}\bar{x}_{2T}^2}$	$\frac{s_{1C}^2}{n_{1C}\bar{x}_{1C}^2}$
SMD	Shared measurement	$v_1 = \frac{1}{n_{1C}} + \frac{1}{n_{1T}} + \frac{d_1^2}{2(n_{1C} + n_{1T})}$ $v_2 = \frac{1}{n_{2C}} + \frac{1}{n_{2T}} + \frac{d_2^2}{2(n_{2C} + n_{2T})}$	$\rho\sqrt{\left(\frac{1}{n_{1C}} + \frac{1}{n_{1T}} + \frac{d_1^2}{2(n_{1C} + n_{1T})}\right) \left(\frac{1}{n_{2C}} + \frac{1}{n_{2T}} + \frac{d_2^2}{2(n_{2C} + n_{2T})}\right)}$
	Shared control	$v_1 = \frac{1}{n_{1C}} + \frac{1}{n_{1T}} + \frac{d_1^2}{2(n_{1C} + n_{1T} + n_{2T})}$ $v_2 = \frac{1}{n_{1C}} + \frac{1}{n_{2T}} + \frac{d_2^2}{2(n_{1C} + n_{1T} + n_{2T})}$	$\frac{1}{n_{1C}} + \frac{d_1 d_2}{2(n_{1C} + n_{1T} + n_{2T})}$

For the 2nd column, see Fig. 2. For the 3rd and 4th column, notations represent: the subscript 1C and 2C (control group for 1st and 2nd effect size, respectively, but for shared control, 1C is used for both effect sizes, but 1C and 2C are the same cohort or set of plots), the subscript 1T and 2T (treatment group for the 1st and 2nd effect size, respectively; for shared groups, 1T and 2T represents different groups of individuals/plots whereas, for shared measurements, 1T and 2T are the same set of individuals/plots), ρ is a correlation in sampling error variance between two measurements, and the other notations are as in Table 1 and the main text (see also [54, 55])

is a more conservative assumption. Or one can run both and use one for the main analysis and the other for sensitivity analysis (for more, see the ‘[Conducting sensitivity analysis and critical appraisal](#)’ section).

The second method overcomes this very issue of unknown ρ by approximating average dependence among sampling variance (and effect sizes) from the data and incorporating such dependence to estimate standard errors (only used in 1 out of 73 studies; Additional file 1). This method is known as ‘robust variance estimation’, RVE, and the original estimator was proposed by Hedges and colleagues in 2010 [57]. Meta-analysis using RVE is relatively new, and this method has been applied to multilevel meta-analytic models only recently [58]. Note that the random-effects model (Eq. 2) and RVE could correctly model both types of non-independence. However, we do not recommend the use of RVE with Eq. 2 because, as we will later show, estimating σ^2 as well as τ^2 will constitute an important part of understanding and gaining more insights from one’s data. We do not yet have a definite recommendation on which method to use to account for non-independence among sampling errors (using the VCV matrix or RVE). This is because no simulation work in the context of multilevel meta-analysis has been done so far, using multilevel meta-analyses [13, 58]. For now, one could use both VCV matrices and RVE in the same model [58] (see also [21]).

Quantifying and explaining heterogeneity 3 Measuring consistencies with heterogeneity

As mentioned earlier, quantifying heterogeneity among effect sizes is an essential component of any meta-analysis. Yet, our survey showed only 28 out of 73 environmental meta-analyses (38.4%; Additional file 1) report at least one index of heterogeneity (e.g., τ^2 , Q , and I^2). Conventionally, the presence of heterogeneity is tested by Cochran’s Q test. However, Q (often noted as Q_T or Q_{total}), and its associated p value, are not particularly informative: the test does not tell us about the extent of heterogeneity (e.g. [10]), only whether heterogeneity is zero or not (when $p < 0.05$). Therefore, for environmental scientists, we recommend two common ways of quantifying heterogeneity from a meta-analytic model: absolute heterogeneity measure (i.e., variance components, τ^2 and σ^2) and relative heterogeneity measure (i.e., I^2 ; see also the “[Notes on visualisation and interpretation](#)” section for another way of quantifying and visualising heterogeneity at the same time, using prediction intervals; see also [59]). We have already covered the absolute measure (Eqs. 2 & 3), so here we explain I^2 , which ranges from 0 to 1 (for some caveats for I^2 , see [60, 61]). The heterogeneity measure, I^2 , for the random-effect model (Eq. 2) can be written as:

$$I^2 = \frac{\tau^2}{\tau^2 + \bar{v}}, \quad (5)$$

$$\bar{v} = \frac{(N_{effect} - 1) \sum_{j=1}^k (1/v_i)}{\left(\sum_{j=1}^k (1/v_i)\right)^2 - \sum_{j=1}^k (1/v_i)^2}, \quad (6)$$

Where \bar{v} is referred to as the typical sampling variance (originally this is called ‘within-study’ variance, as in Eq. 2, and note that in this formulation, within-study effect and the effect of sampling error is confounded; see [62, 63]; see also [64]) and the other notations are as above. As you can see from Eq. 5, we can interpret I^2 as relative variation due to differences between studies (between-study variance) or relative variation not due to sampling variance.

By seeing I^2 as a type of interclass correlation (also known as repeatability [65]), we can generalize I^2 to multilevel models. In the case of Eq. 3 ([40, 66]; see also [52]), we have:

$$I_{total}^2 = \frac{\tau^2 + \sigma^2}{\tau^2 + \sigma^2 + \bar{v}} \quad (7)$$

Because we can have two more I^2 , Eq. 7 is written as I_{total}^2 ; these other two are I_{study}^2 and I_{effect}^2 , respectively:

$$I_{study}^2 = \frac{\tau^2}{\tau^2 + \sigma^2 + \bar{v}}, \quad (8)$$

$$I_{effect}^2 = \frac{\sigma^2}{\tau^2 + \sigma^2 + \bar{v}} \quad (9)$$

I_{total}^2 represents relative variance due to differences both between and within studies (between- and within-study variance) or relative variation not due to sampling variance, while I_{study}^2 is relative variation due to differences between studies, and I_{effect}^2 is relative variation due to differences within studies (Fig. 3A). Once heterogeneity is quantified (note almost all data will have non-zero heterogeneity and an earlier meta-meta-analysis suggests in ecology, we have on average, I^2 close to 90% [66]), it is time to fit a meta-regression model to explain the heterogeneity. Notably, the magnitude of I_{study}^2 (and τ^2) and I_{effect}^2 (and σ^2) can already inform you which predictor variable (usually referred to as ‘moderator’) is likely to be important, which we explain in the next section.

Explaining variance with meta-regression 14

We can extend the multilevel model (Eq. 3) to a meta-regression model with one moderator (also known as predictor, independent, explanatory variable, or fixed factor), as below:

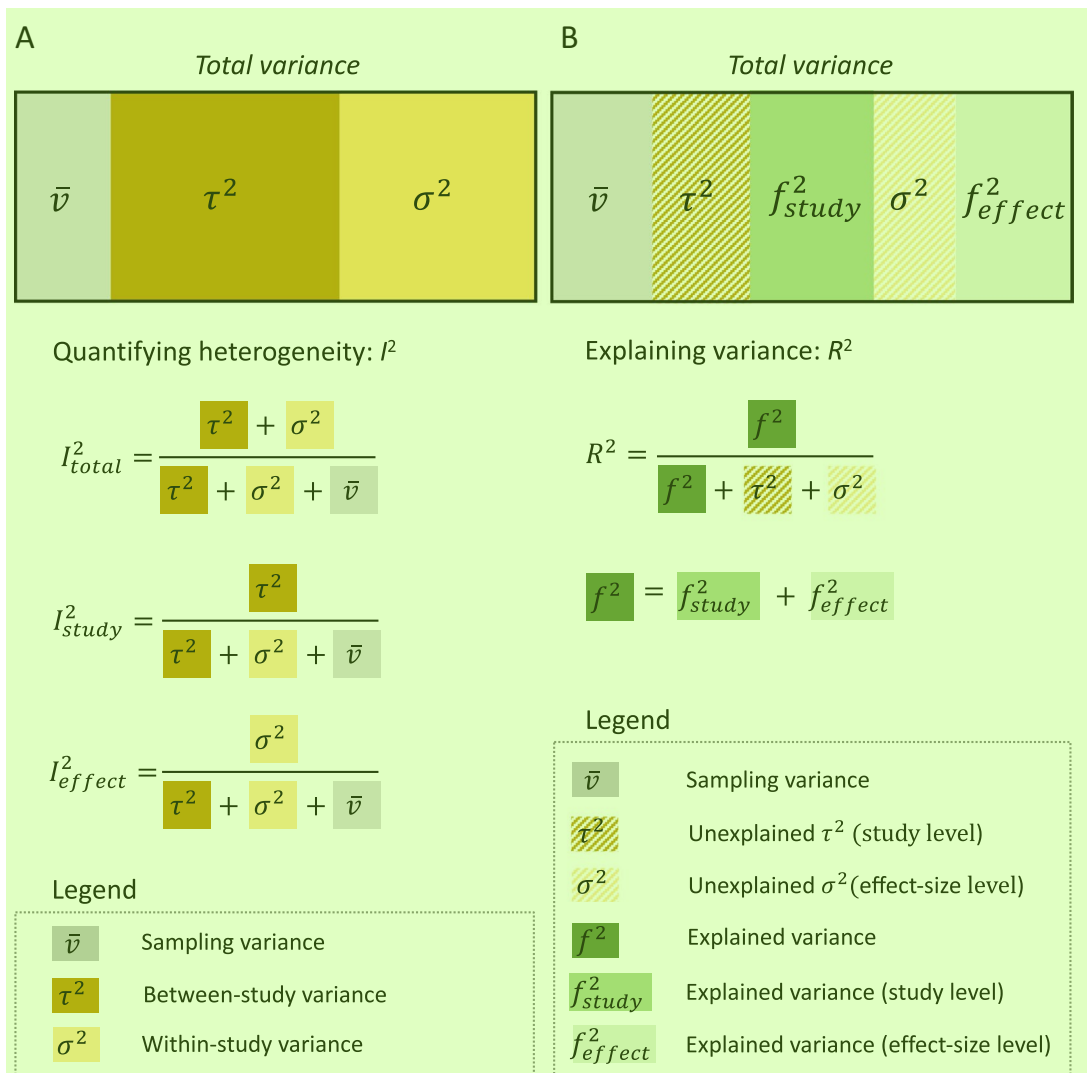


Fig. 3 Visualisation of variation (heterogeneity) partitioned into different variance components: **A** quantifying different types of I^2 from a multilevel model (3-level; see Fig. 1C) and **B** variance explained, R^2 , by moderators. Note that different levels of variances would be explained, depending on which level a moderator belongs to (study level and effect-size level)

$$z_i = \beta_0 + \beta_1 x_{1j[i]} + u_{j[i]} + e_i + m_i, \quad (10)$$

where β_1 is a slope of the moderator (x_1), $x_{1j[i]}$ denotes the value of x_1 , corresponding to the j th study (and the i th effect sizes). Equation (10) (meta-regression) is comparable to the simplest regression with the intercept (β_0) and slope (β_1). Notably, $x_{1j[i]}$ differs between studies and, therefore, it will mainly explain the variance component, τ^2 (which relates to I^2_{study}). On the other hand, if noted like x_{1i} , this moderator would vary within studies or at the level of effect sizes, therefore, explaining σ^2 (relating to I^2_{effect}). Therefore, when τ^2 (I^2_{study}), or σ^2 (I^2_{effect}), is close to zero, there will be little point fitting a moderator(s) at the level of studies, or effect sizes, respectively.

As in multiple regression, we can have multiple (multi-moderator) meta-regression, which can be written as:

$$z_i = \beta_0 + \sum_{h=1}^q \beta_h x_{h[i]} + u_{j[i]} + e_i + m_i, \quad (11)$$

where $\sum_{h=1}^q \beta_h x_{h[i]}$ denotes the sum of all the moderator effects, with q being the number of slopes (starting with $h=1$). We note that q is not necessarily the number of moderators. This is because when we have a categorical moderator, which is common, with more than two levels (e.g., method A, B & C), the fixed effect part of the formula is $\beta_0 + \beta_1 x_1 + \beta_2 x_2$, where x_1 and x_2 are 'dummy' variables, which code whether the i th effect size belongs to, for example, method B or C, with β_1 and β_2

being contrasts between A and B and between A and C, respectively (for more explanations of dummy variables, see our tutorial page [https://itchyshin.github.io/Meta-analysis_tutorial/]; also see [67, 68]). Traditionally, researchers conduct separate meta-analyses per different groups (known as ‘sub-group analysis’), but we prefer a meta-regression approach with a categorical variable, which is statistically more powerful [40]. Also, importantly, what can be used as a moderator(s) is very flexible, including, for example, individual/plot characteristics (e.g., age, location), environmental factors (e.g., temperature), methodological differences between studies (e.g., randomization), and bibliometric information (e.g., publication year; see more in the section ‘Checking for publication bias and robustness’). Note that moderators should be decided and listed a priori in the meta-analysis plan (i.e., a review protocol or pre-registration).

As with meta-analysis, the Q -test (Q_m or $Q_{moderator}$) is often used to test the significance of the moderator(s). To complement this test, we can also quantify variance explained by the moderator(s) using R^2 . We can define R^2 using Eq. (11) as:

$$R^2 = \frac{f^2}{f^2 + \tau^2 + \sigma^2}, \quad (12)$$

$$f^2 = \text{Var} \left(\sum_{h=1}^q \beta_h x_{h[i]} \right), \quad (13)$$

where R^2 is known as marginal R^2 (sensu [69, 70]; cf. [71]), f^2 is the variance due to the moderator(s), and $(f^2 + \tau^2 + \sigma^2)$ here equals to $(\tau^2 + \sigma^2)$ in Eq. 7, as f^2 ‘absorbs’ variance from τ^2 and/or σ^2 . We can compare the similarities and differences in Fig. 3B where we denote a part of f^2 originating from τ^2 as f_{study}^2 while σ^2 as f_{effect}^2 . In a multiple meta-regression model, we often want to find a model with the ‘best’ or an adequate set of predictors (i.e., moderators). R^2 can potentially help such a model selection process. Yet, methods based on information criteria (such as Akaike information criterion, AIC) may be preferable. Although model selection based on the information criteria is beyond the scope of the paper, we refer the reader to relevant articles (e.g., [72, 73]), and we show an example of this procedure in our online tutorial (https://itchyshin.github.io/Meta-analysis_tutorial/).

Notes on visualisation and interpretation

Visualization and interpretation of results is an essential part of a meta-analysis [74, 75]. Traditionally, a forest plot

is used to display the values and 95% of confidence intervals (CIs) for each effect size and the overall effect and its 95% CI (the diamond symbol is often used, as shown in Fig. 4A). More recently, adding a 95% prediction interval (PI) to the overall estimate has been strongly recommended because 95% PIs show a predicted range of values in which an effect size from a new study would fall, assuming there is no sampling error [76]. Here, we think that examining the formulas for 95% CIs and PIs for the overall mean (from Eq. 3) is illuminating:

$$95\%CI = \beta_0 \pm t_{df[\alpha=0.05]} se(\beta_0), \quad (14)$$

$$95\%PI = \beta_0 \pm t_{df[\alpha=0.05]} \sqrt{se^2(\beta_0) + \tau^2 + \sigma^2}, \quad (15)$$

where $t_{df[\alpha=0.05]}$ denotes the t value with the degree of freedom, df , at 97.5 percentile (or $\alpha = 0.05$) and other notations are as above. In a meta-analysis, it has been conventional to use z value 1.96 instead of $t_{df[\alpha=0.05]}$, but simulation studies have shown the use of t value over z value reduces Type 1 errors under many scenarios and, therefore, is recommended (e.g., [13, 77]). Also, it is interesting to note that by plotting 95% PIs, we can visualize heterogeneity as Eq. 15 includes τ^2 and σ^2 .

A ‘forest’ plot can become quickly illegible as the number of studies (effect sizes) becomes large, so other methods of visualizing the distribution of effect sizes have been suggested. Some suggested to present a ‘caterpillar’ plot, which is a version of the forest plot, instead (Fig. 4B; e.g., [78]). We here recommend an ‘orchard’ plot, as it can present results across different groups (or a result of meta-regression with a categorical variable), as shown in Fig. 4C [78]. For visualization of a continuous variable, we suggest what is called a ‘bubble’ plot, shown in Fig. 4D. Visualization not only helps us interpret meta-analytic results, but can also help to identify something we may not see from statistical results, such as influential data points and outliers that could threaten the robustness of our results.

Checking for publication bias and robustness

Detecting and correcting for publication bias

Checking for and adjusting for any publication bias is necessary to ensure the validity of meta-analytic inferences [79]. However, our survey showed almost half of the environmental meta-analyses (46.6%; 34 out of 73 studies; Additional file 1) neither tested for nor corrected for publication bias (cf. [14–16]). The most popular methods used were: (1) graphical tests using funnel plots (26 studies; 35.6%), (2) regression-based tests such as Egger regression (18 studies; 24.7%), (3) Fail-safe number

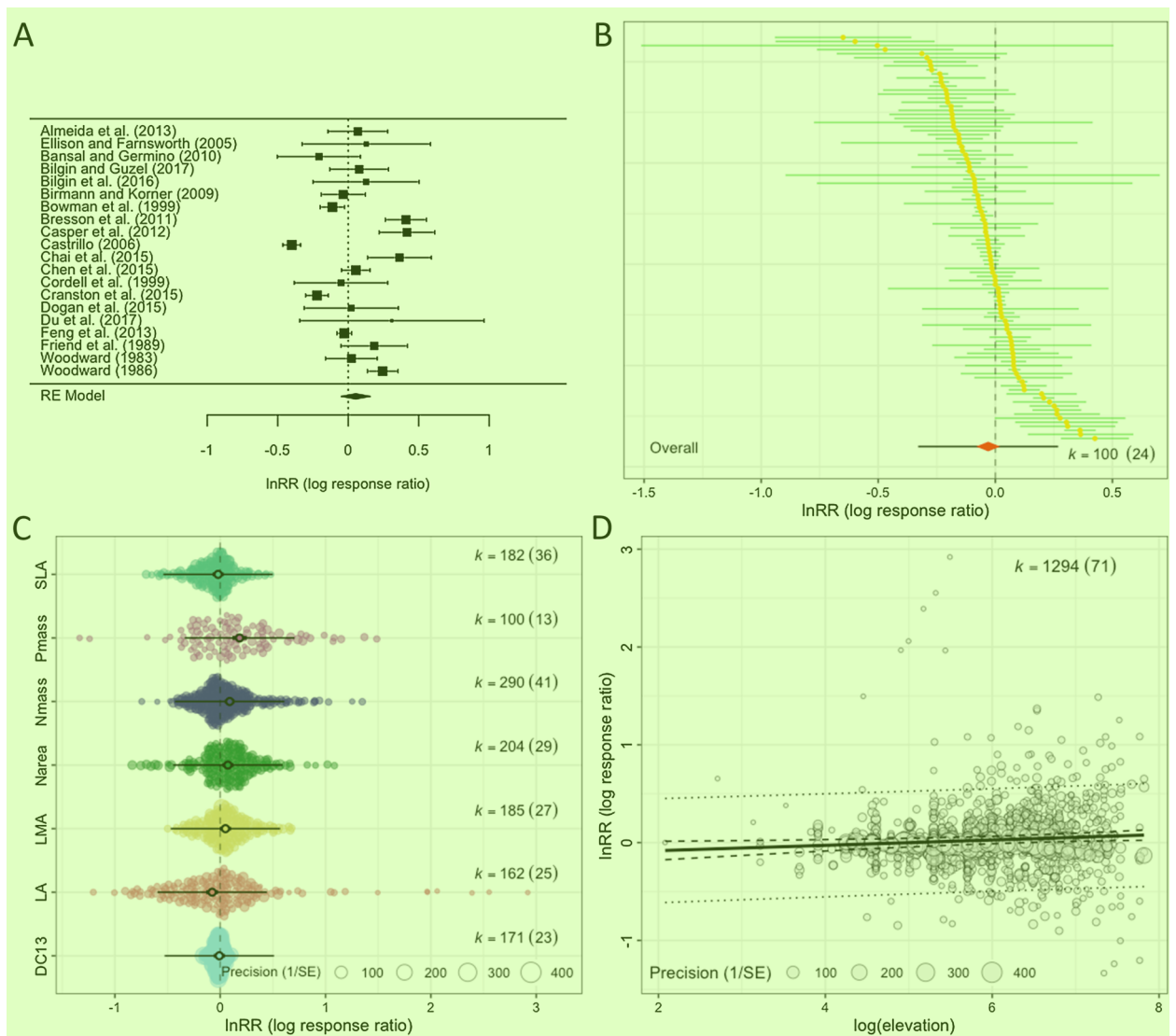


Fig. 4 Different types of plots useful for a meta-analysis using data from Midolo et al. [133]: **A** a typical forest plot with the overall mean shown as a diamond at the bottom (20 effect sizes from 20 studies are used), **B** a caterpillar plot (100 effect sizes from 24 studies are used), **C** an orchard plot of categorical moderator with seven levels (all effect sizes are used), and **D** a bubble plot of a continuous moderator. Note that the first two only show confidence intervals, while the latter two also show prediction intervals (see the text for more details)

tests (12 studies; 16.4%), and (4) trim-and-fill tests (10 studies; 13.7%). We recently showed that these methods are unsuitable for datasets with non-independent effect sizes, with the exception of funnel plots [80] (for an example of funnel plots, see Fig. 5A). This is because these methods cannot deal with non-independence in the same way as the fixed-effect and random-effects models. Here, we only introduce a two-step method for multilevel models that can both detect and correct for publication bias [80] (originally proposed by [81, 82]), more specifically, the “small study effect” where an effect size value from a small-sample-sized study can be much larger in

magnitude than a ‘true’ effect [83, 84]. This method is a simple extension of Egger’s regression [85], which can be easily implemented by using Eq. 10:

$$z_i = \beta_0 + \beta_1 \sqrt{\frac{1}{\tilde{n}_i}} + u_{j[i]} + e_i + m_i, \quad (16)$$

$$z_i = \beta_0 + \beta_1 \left(\frac{1}{\tilde{n}_i} \right) + u_{j[i]} + e_i + m_i, \quad (17)$$

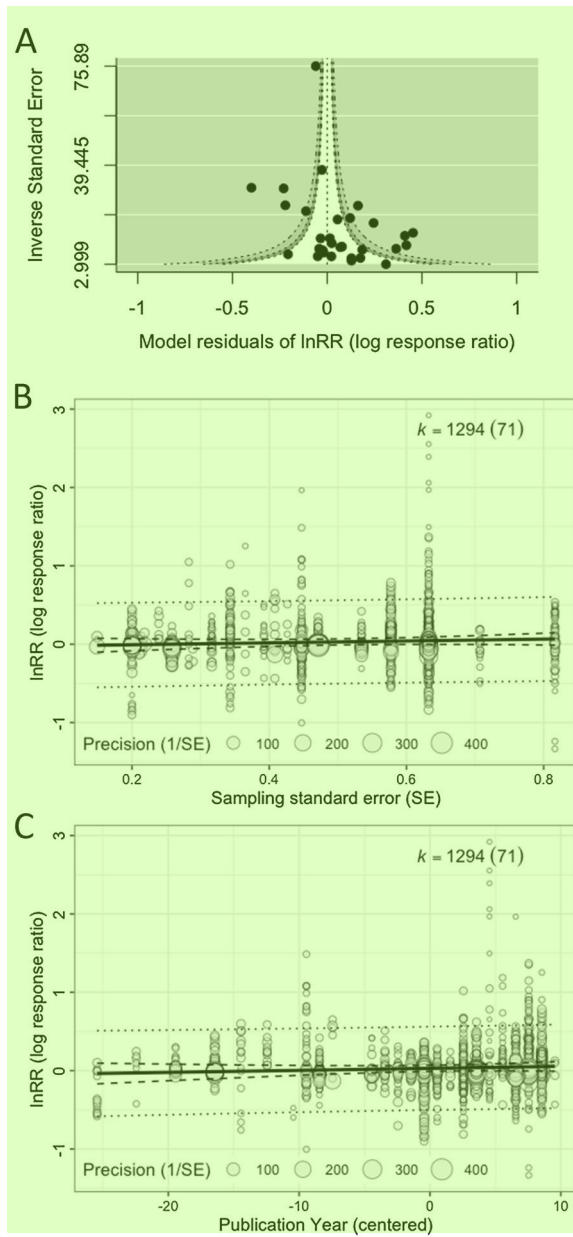


Fig. 5 Different types of plots for publication bias tests: **A** a funnel plot using model residuals, showing a funnel (white) that shows the region of statistical non-significance (30 effect sizes from 30 studies are used; note that we used the inverse of standard errors for the y-axis, but for some effect sizes, sample size or 'effective' sample size may be more appropriate), **B** a bubble plot visualising a multilevel meta-regression that tests for the small study effect (note that the slope was non-significant: $b = 0.120$, 95% CI = $[-0.095, 0.334]$; all effect sizes are used), and **C** a bubble plot visualising a multilevel meta-regression that tests for the decline effect (the slope was non-significant: $b = 0.003$, 95% CI = $[-0.002, 0.008]$)

where \tilde{n}_i is known as effective sample size; for Zr and proportion it is just n_i , and for SMD and lnRR, it is $n_{iC}n_{iT}/(n_{iC} + n_{iT})$, as in Table 2. When β_1 is significant,

we conclude there exists a small-study effect (in terms of a funnel plot, this is equivalent to significant funnel asymmetry). Then, we fit Eq. 17 and we look at the intercept β_0 , which will be a bias-corrected overall estimate [note that β_0 in Eq. (16) provides less accurate estimates when non-zero overall effects exist [81, 82]; Fig. 5B]. An intuitive explanation of why β_0 (Eq. 17) is the 'bias-corrected' estimate is that the intercept represents $1/\tilde{n}_i = 0$ (or $\tilde{n}_i = \infty$); in other words, β_0 is the estimate of the overall effect when we have a very large (infinite) sample size. Of note, appropriate bias correction requires a selection-mode-based approach although such an approach is yet to be available for multilevel meta-analytic models [80].

Conveniently, this proposed framework can be extended to test for another type of publication bias, known as time-lag bias, or the decline effect, where effect sizes tend to get closer to zero over time, as larger or statistically significant effects are published more quickly than smaller or non-statistically significant effects [86, 87]. Again, a decline effect can be statistically tested by adding year to Eq. (3):

$$z_i = \beta_0 + \beta_1 c(\text{year}_{j[i]}) + u_{j[i]} + e_i + m_i, \quad (18)$$

where $c(\text{year}_{j[i]})$ is the mean-centred publication year of a particular study (study j and effect size i); this centring makes the intercept β_0 meaningful, representing the overall effect estimate at the mean value of publication years (see [68]). When the slope is significantly different from 0, we deem that we have a decline effect (or time-lag bias; Fig. 5C).

However, there may be some confounding moderators, which need to be modelled together. Indeed, Egger's regression (Eqs. 16 and 17) is known to detect the funnel asymmetry when there is little heterogeneity; this means that we need to model $\sqrt{1/\tilde{n}_i}$ with other moderators that account for heterogeneity. Given this, we probably should use a multiple meta-regression model, as below:

$$z_i = \beta_0 + \beta_1 \sqrt{\frac{1}{\tilde{n}_i}} + \beta_2 c(\text{year}_{j[i]}) + \sum_{h=3}^q \beta_h x_{h[i]} + u_{j[i]} + e_i + m_i, \quad (19)$$

where $\sum_{h=3}^q \beta_h x_{h[i]}$ is the sum of the other moderator effects apart from the small-study effect and decline effect, and other notations are as above (for more details see [80]). We need to carefully consider which moderators should go into Eq. 19 (e.g., fitting all moderators or using an AIC-based model selection method; see [72, 73]). Of relevance, when running complex models, some model parameters cannot be estimated well, or they are not 'identifiable' [88]. This is especially so for variance components (random-effect part) rather than regression coefficients (fixed-effect part). Therefore, it is advisable

to check whether model parameters are all identifiable, which can be checked using the *profile* function in *metafor* (for an example, see our tutorial webpage [https://itchyshin.github.io/Meta-analysis_tutorial/]).

Conducting sensitivity analysis and critical appraisal

Sensitivity analysis explores the robustness of meta-analytic results by running a different set of analyses from the original analysis, and comparing the results (note that some consider publication bias tests a part of sensitivity analysis; [11]). For example, we might be interested in assessing how robust results are to the presence of influential studies, to the choice of method for addressing non-independence, or weighting effect sizes. Unfortunately, in our survey, only 37% of environmental meta-analyses (27 out of 73) conducted sensitivity analysis (Additional file 1). There are two general and interrelated ways to conduct sensitivity analyses [73, 89, 90]. The first one is to take out influential studies (e.g., outliers) and re-run meta-analytic and meta-regression models. We can also systematically take each effect size out and run a series of meta-analytic models to see whether any resulting overall effect estimates are different from others; this method is known as ‘leave-one-out’, which is considered less subjective and thus recommended.

The second way of approaching sensitivity analysis is known as subset analysis, where a certain group of effect sizes (studies) will be excluded to re-run the models without this group of effect sizes. For example, one may want to run an analysis without studies that did not randomize samples. Yet, as mentioned earlier, we recommend using meta-regression (Eq. 13) with a categorical variable of randomization status (‘randomized’ or ‘not randomized’), to statistically test for an influence of moderators. It is important to note that such tests for risk of bias (or study

quality) can be considered as a way of quantitatively evaluating the importance of study features that were noted at the stage of critical appraisal, which is an essential part of any systematic review (see [11, 91]). In other words, we can use meta-regression or subset analysis to quantitatively conduct critical appraisal using (study-level) moderators that code, for example, blinding, randomization, and selective reporting. Despite the importance of critical appraisal ([91]), only 4 of 73 environmental meta-analyses (5.6%) in our survey assessed the risk of bias in each study included in a meta-analysis (i.e., evaluating a primary study in terms of the internal validity of study design and reporting; Additional file 1). We emphasize that critically appraising each paper or checking them for risk of bias is an extremely important topic. Also, critical appraisal is not restricted to quantitative synthesis. Therefore, we do not cover any further in this paper for more, see [92, 93]).

Notes on transparent reporting and open archiving

For environmental systematic reviews and maps, there are reporting guidelines called RepOrting standards for Systematic Evidence Syntheses in environmental research, ROSES [94] and synthesis assessment checklist, the Collaboration for Environmental Evidence Synthesis Appraisal Tool (CEESAT; [95]). However, these guidelines are somewhat limited in terms of reporting quantitative synthesis because they cover only a few core items. These two guidelines are complemented by the Preferred Reporting Items for Systematic Reviews and Meta-Analyses for Ecology and Evolutionary Biology (PRISMA-EcoEvo; [96]; cf. [97, 98]), which provides an extended set of reporting items covering what we have described above. Items 20–24 from PRISMA-EcoEvo are most relevant: these items outline what should be

Table 4 Items relevant to reporting results for a meta-analysis from the Preferred Reporting Items for Systematic reviews and Meta-Analysis for Ecology and Evolutionary Biology (PRISMA-EcoEvo; [96])

Item	Description
20: Sample sizes and study characteristics	“Report the number of studies and effect size for data included in meta-analyses and subsets of data included in meta-regressions. Provide a summary of key characteristics for reported outcomes (either in text or figures; e.g., one quarter of effect sizes reported for vertebrates and the rest invertebrates) and their limitations (e.g., collinearity and overlaps between moderators), including characteristics related individual study quality (risk of bias).”
21: Meta-analysis	“Provide a quantitative synthesis of results across studies, including estimates for the main effect size, with confidence/credible intervals.”
22: Heterogeneity	“Report indicators of heterogeneity in the estimated effect (e.g. I^2 , τ^2 and other variance components).”
23: Meta-regression	“Provide estimates of meta-regression slopes (i.e. regression coefficients) for all variables that were assessed for their contribution to heterogeneity. Include confidence/credible intervals, and report interactions if they were included. Describe outcomes from model selection, if done (e.g. R^2 and AIC).”
24: Outcomes of publication bias and sensitivity analysis	“Provide results for the assessments of the risks of bias (e.g. Egger’s regression, funnel plots) and robustness of the review’s results (e.g. subgroup analyses, meta-regression of study quality, results from alternative methods of analysis, and temporal trends)”

reported in the Methods section: (i) sample sizes and study characteristics, (ii) meta-analysis, (iii) heterogeneity, (iv) meta-regression and (v) outcomes of publication bias and sensitivity analysis (see Table 4). Our survey, as well as earlier surveys, suggest there is a large room for improvement in the current practice ([14–16]). Incidentally, the orchard plot is well aligned with Item 20, as this plot type shows both the number of effect sizes and studies for different groups (Fig. 4C). Further, our survey of environmental meta-analyses highlighted the poor standards of data openness (with 24 studies sharing data: 32.9%) and code sharing (7 studies: 29.2%; Additional file 1). Environmental scientists must archive their data as well as their analysis code in accordance with the FAIR principles (Findable, Accessible, Interoperable, and Reusable [99]) using dedicated depositories such as Dryad, FigShare, Open Science Framework (OSF), Zenodo or others (cf. [100, 101]), preferably not on publisher's web-pages (as paywall may block access). However, archiving itself is not enough; data requires metadata (detailed descriptions) and the code needs to also be FAIR [102, 103].

Other relevant and advanced issues 2

Scale dependence

The issue of scale dependence is a unique yet widespread problem in environmental sciences (see [7, 104]); our literature survey indicated three quarters of the environmental meta-analyses (56 out of 73 studies) have inferences that are potentially vulnerable to scale-dependence [105]. For example, studies that set out to compare group means in biodiversity measures, such as species richness, can vary as a function of the scale (size) of the sampling unit. When the unit of replication is a plot (not an individual animal or plant), the aerial size of a plot (e.g., 100 cm² or 1 km²) will affect both the precision and accuracy of effect size estimates (e.g., lnRR and SMD). In general, a study with larger plots might have more accurately estimated species richness differences, but less precisely than a study with smaller plots and greater replication. Lower replication means that our sampling variance estimates are likely to be misestimated, and the study with larger plots will generally have less weight than the study with smaller plots, due to higher sampling variance. Inaccurate variance estimates in little-replicated ecological studies are known to cause an accumulating bias in precision-weighted meta-analysis, requiring correction [43]. To assess the potential for scale-dependence, it is recommended that analysts test for possible covariation among plot size, replication, variances, and effect sizes [104]. If detected, analysts should use an effect size measure that is less sensitive to scale dependence (lnRR), and could use the size of a plot as a

moderator in meta-regression, or alternatively, they consider running an unweighted model ([7]; note that only 12%, 9 out of 73 studies, accounted for sampling area in some way; Additional file 1).

Missing data 5

In many fields, meta-analytic data almost always encompass missing values see [106–108]. Broadly, we have two types of missing data in meta-analyses [109, 110]: (1) missing data in standard deviations or sample sizes, associated with means, preventing effect size calculations (Table 2), and (2) missing data in moderators. There are several solutions for both types. The best, and first to try, should be contacting the authors. If this fails, we can potentially 'impute' missing data. Single imputation methods using the strong correlation between standard deviation and mean values (known as mean–variance relationship) are available, although single imputation can lead to Type I error [106, 107] (see also [43]) because we do not model the uncertainty of imputation itself. Contrastingly, multiple imputation, which creates multiple versions of imputed datasets, incorporates such uncertainty. Indeed, multiple imputation is a preferred and proven solution for missing data in effect sizes and moderators [109, 110]. Yet, correct implementation can be challenging (see [110]). What we require now is an automated pipeline of merging meta-analysis and multiple imputation, which accounts for imputation uncertainty, although it may be challenging for complex meta-analytic models. Fortunately, however, for lnRR, there is a series of new methods that can perform better than the conventional method and which can deal with missing SDs [44]; note that these methods do not deal with missing moderators. Therefore, where applicable, we recommend these new methods, until an easy-to-implement multiple imputation workflow arrives.

Complex non-independence 7

Above, we have only dealt with the model that includes study identities as a clustering/grouping (random) factor. However, many datasets are more complex, with potentially more clustering variables in addition to the study identity. It is certainly possible that an environmental meta-analysis contains data from multiple species. Such a situation creates an interesting dependence among effect sizes from different species, known as phylogenetic relatedness, where closely related species are more likely to be similar in effect sizes compared to distantly related ones (e.g., mice vs. rats and mice vs. sparrows). Our multilevel model framework is flexible and can accommodate phylogenetic relatedness. A phylogenetic multilevel meta-analytic model can be written as [40, 111, 112]:

$$z_i = \beta_0 + a_{k[i]} + s_{k[i]} + u_{j[i]} + e_i + m_i, \quad (20)$$

$$a_k \sim N(0, \omega^2 A), s_k \sim N(0, \gamma^2), u_j \sim N(0, \tau^2), \\ e_i \sim N(0, \sigma^2), \text{ \& } m_i \sim N(0, v_i),$$

where $a_{k[i]}$ is the phylogenetic (species) effect for the k th species (effect size i ; $N_{\text{effect}} (i=1, 2, \dots, N_{\text{effect}}) > N_{\text{study}} (j=1, 2, \dots, N_{\text{study}}) > N_{\text{species}} (k=1, 2, \dots, N_{\text{species}})$), normally distributed with $\omega^2 A$ where A is the phylogenetic variance and A is a correlation matrix coding how close each species are to each other and ω^2 is the phylogenetic variance, $s_{k[i]}$ is the non-phylogenetic (species) effect for the k th species (effect size i), normally distributed with the variance of γ^2 (the non-phylogenetic variance), and other notations are as above. It is important to realize that A explicitly models relatedness among species, and we do need to provide this correlation matrix, using a distance relationship usually derived from a molecular-based phylogenetic tree (for more details, see [40, 111, 112]). Some may think that the non-phylogenetic term ($s_{k[i]}$) is unnecessary or redundant because $s_{k[i]}$ and the phylogenetic term ($a_{k[i]}$) are both modelling variance at the species level. However, a simulation recently demonstrated that failing to have the non-phylogenetic term ($s_{k[i]}$) will often inflate the phylogenetic variance ω^2 , leading to an incorrect conclusion that there is a strong phylogenetic signal (as shown in [112]). The non-phylogenetic variance (γ^2) arises from, for example, ecological similarities among species (herbivores *vs.* carnivores or arboreal *vs.* ground-living) not phylogeny [40].

Like phylogenetic relatedness, effect sizes arising from closer geographical locations are likely to be more correlated [113]. Statistically, spatial correlation can be also modelled in a manner analogous to phylogenetic relatedness (i.e., rather than a phylogenetic correlation matrix, A , we fit a spatial correlation matrix). For example, Maire and colleagues [114] used a meta-analytic model with spatial autocorrelation to investigate the temporal trends of fish communities in the network of rivers in France. We note that a similar argument can be made for temporal correlation, but in many cases, temporal correlations could be dealt with, albeit less accurately, as a special case of ‘shared measurements’, as in Fig. 2. An important idea to take away is that one can model different, if not all, types of non-independence as the random factor(s) in a multilevel model.

Advanced techniques 5

Here we touch upon five advanced meta-analytic techniques with potential utility for environmental sciences, providing relevant references so that interested readers

can obtain more information on these advanced topics. The first one is the meta-analysis of magnitudes, or absolute values (effect sizes), where researchers may be interested in deviations from 0, rather than the directionality of the effect [115]. For example, Cohen and colleagues [116] investigated absolute values of phenological responses, as they were concerned with the magnitudes of changes in phenology rather than directionality.

The second method is the meta-analysis of interaction where our focus is on synthesizing the interaction effect of, usually, 2×2 factorial design (e.g., the effect of two simultaneous environmental stressors [54, 117, 118]; see also [119]). Recently, Siviter and colleagues [120] showed that agrochemicals interact synergistically (i.e., non-additively) to increase the mortality of bees; that is, two agrochemicals together caused more mortality than the sum of mortalities of each chemical.

Third, network meta-analysis has been heavily used in medical sciences; network meta-analysis usually compares different treatments in relation to placebo and ranks these treatments in terms of effectiveness [121]. The very first ‘environmental’ network meta-analysis, as far as we know, investigated the effectiveness of ecosystem services among different land types [122].

Fourth, a multivariate meta-analysis is where one can model two or more different types of effect sizes with the estimation of pair-wise correlations between different effect sizes. The benefit of such an approach is known as the ‘borrowing of strength’, where the error of fixed effects (moderators; e.g., b_0 and b_1) can be reduced when different types of effect sizes are correlated (i.e., $se(b_0)$ and $se(b_1)$ can be smaller [123]). For example, it is possible for \lnRR (differences in mean) and \lnVR (differences in SDs) to be modelled together (cf. [124]).

Fifth, as with network meta-analysis, there has been a surge in the use of ‘individual participants data’, called ‘IPD meta-analysis’, in medical sciences [125, 126]. The idea of IPD meta-analysis is simple—rather than using summary statistics reported in papers (sample means and variances), we directly use raw data from all studies. We can either model raw data using one complex multilevel (hierarchical) model (one-step method) or calculate statistics for each study and use a meta-analysis (two-step method; note that both methods will usually give the same results). Study-level random effects can be incorporated to allow the response variable of interest to vary among studies, and overall effects correspond to fixed, population-level estimates. The use of IPD or ‘full-data analyses’ has also surged in ecology, aided by open-science policies that encourage the archival of raw data alongside articles, and initiatives that synthesise raw data (e.g., PREDICTS [127], BioTime [128]). In health disciplines, such meta-analyses are considered the ‘gold

standard' [129], owing to their potential for resolving issues regarding study-specific designs and confounding variation, and it is unclear whether and how they might resolve issues such as scale dependence in environmental meta-analyses [104, 130].

Conclusions

In this article, we have attempted to describe the most practical ways to conduct quantitative synthesis, including meta-analysis, meta-regression, and publication bias tests. In addition, we have shown that there is much to be improved in terms of meta-analytic practice and reporting via a survey of 73 recent environmental meta-analyses. Such improvements are urgently required, especially given the potential influence that environmental meta-analyses can have on policies and decision-making [8]. So often, meta-analysts have called for better reporting of primary research (e.g. [131, 132]), and now this is the time to raise the standards of reporting in meta-analyses. We hope our contribution will help to catalyse a turning point for better practice in quantitative synthesis in environmental sciences. We remind the reader most of what is described is implemented in the *R* environment on our tutorial webpage and researchers can readily use the proposed models and techniques (https://itchyshin.github.io/Meta-analysis_tutorial/). Finally, meta-analytic techniques are always developing and improving. It is certainly possible that in the future, our proposed models and related methods will become dated, just as the traditional fixed-effect and random-effects models already are. Therefore, we must endeavour to be open-minded to new ways of doing quantitative research synthesis in environmental sciences.

Supplementary Information

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Additional file 1: The survey of meta-analyses in environmental sciences.

Additional file 2: The hands-on R tutorial.

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Author contributions

SN was commissioned to write this article so he assembled a team of co-authors. SN discussed the idea with YY, ELM, RS and ML, and all of them contributed to the design of this review. ML led the survey working with YY and ELM, while YY led the creation of the accompanying webpage working with RS. SN supervised all aspects of this work and wrote the first draft, which

was commented on, edited, and therefore, significantly improved by the other co-authors. All authors read and approved the final manuscript.

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The authors report no competing interests.

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